

GUM/Supplement 1 – Numerical Implementation

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Recent Development in Measurement Uncertainty
Lisbon 2011



MUSE – Measurement Uncertainty Simulation and Evaluation

PhD thesis of

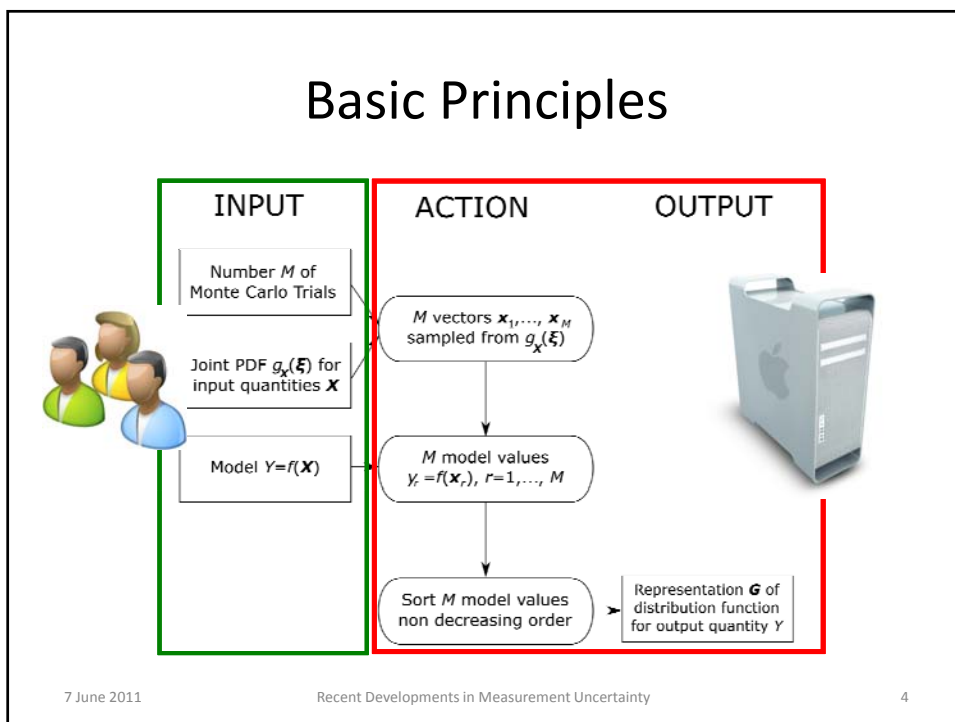
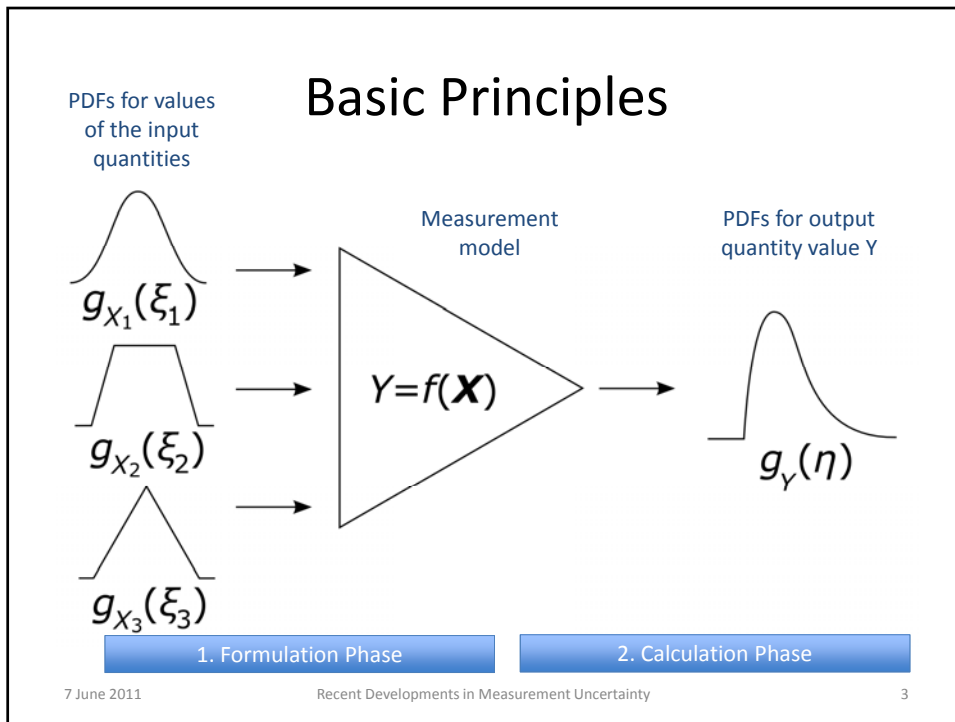
- Dr. Marco Wolf
- Dr. Martin E. Müller



Swiss Federal Institute of Technology (ETH) Zürich

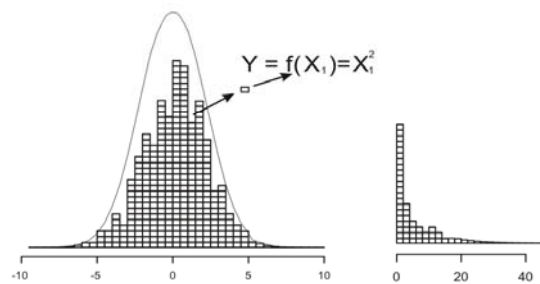
- Prof Walter Gander – Institute of Scientific Computing





Monte Carlo Method

- Sample of the input quantities
- Evaluate the given model for the given values
- Determines an approximation for the PDF of the output quantities



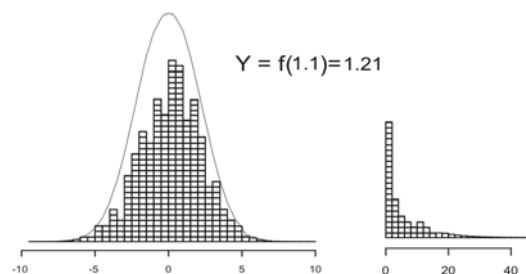
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Monte Carlo Method

- Sample of the input quantities
- Evaluate the given model for the given values
- Determines an approximation for the PDF of the output quantities



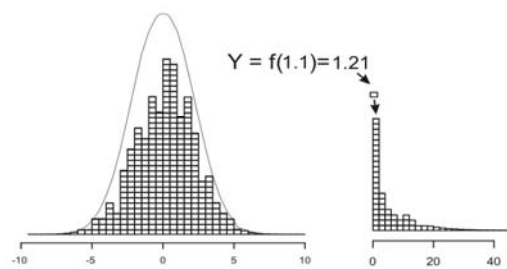
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Monte Carlo Method

- Sample of the input quantities
- Evaluate the given model for the given values
- Determines an approximation for the PDF of the output quantities



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Monte Carlo Method

Random number generation for the input quantities

- Generation of random numbers of a rectangular distribution $U(0, 1)$
 - Use these random numbers to generate the random numbers of the PDF of an input quantity
 - The more random numbers the “better” accuracy
- Basis for an efficient implementation is the efficient generation of uniformly distributed random numbers

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Monte Carlo Method

Efficient generation of U(0,1)

- Not every random number generator is suited for MC (e.g. Excel, Microsoft Visual C# etc.)
- Wichman-Hill
 - Proposed by GS1
 - “easy” to implement
 - Period $\approx 10^{37}$
- Mersenne Twister
 - “State of the art”
 - Standard implementation available
 - Period $\approx 10^{6000}$

Monte Carlo Method

Efficient Evaluation of the Equation of the Measurand

- An evaluation of the model function is needed for each value of the PDFs of the input quantities
- Interpretation of variables/mathematical functions (Parse)
- Time consuming procedures
- Economizing of these procedures means gains in efficiency

Monte Carlo Method

Efficient Evaluation of the Equation of the Measurand

- *MUSE* uses “block-by-block” evaluation
 - Buffer method with 10^4 values per block
 - All functions are calculated within these blocks
 - Model function has only to be “parsed” once for each block
- Parse the model function in the so call Postfix notation (reverse polish notation)
 - No bracketing needed

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Monte Carlo Method

Efficient Summarization of the Results

- *MUSE* generates “vast” files with possible values of the PDF of the measurand
 - 10^8 evaluations \approx 800 MB (binary)
- GS1 demands to sort all values
- Sorting is very time consuming (especially with a large number of simulations)

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Monte Carlo Method

Efficient Summarization of the Results

- Statistical values (e.g. mean, standard deviation) are calculated for each block (block-by-block)
- The overall statistical parameters are calculated as mean values of the parameters of the blocks
- Different to GS1!
 - Convergence has been proven
 - Optional overall sorting has been implemented

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Modeling Concept

- GUM and GS1 describe methods to calculate the measurement uncertainty → calculator kernel
- GUM and GS1 do not provide a basic concept for the dealing with comprehensive and elaborate measurement scenarios
- *MUSE* supports the advanced user for building, organizing and comprehension of models
 - Stored as pure text files
 - Open and easily adjustable format
 - Strict language definition in XML

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Modeling Concept

Example: Gauge block calibration



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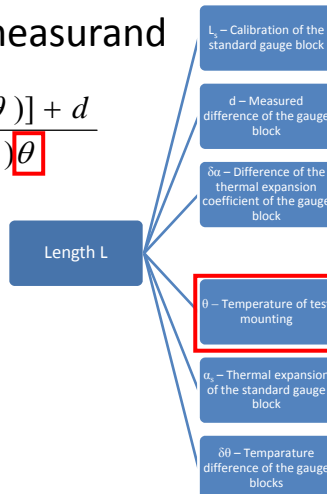
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Modeling Concept

- Equation of the measurand

$$L = \frac{L_s [1 + \alpha_s (\theta - \delta\theta)] + d}{1 + (\alpha_s + \delta\alpha) \theta}$$



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Modeling Concept

- Equation of the measurand

$$L = \frac{L_s [1 + \alpha_s (\theta - \delta\theta)] + d}{1 + (\alpha_s + \delta\alpha) \theta}$$
- Sub-influences

$$\theta = \theta_0 + \Delta$$

$$d = D + d_1 + d_2$$

Length L

- L_s – Calibration of the standard gauge block
- d – Measured difference of the gauge block
- δ_α – Difference of the thermal expansion coefficient of the gauge block
- θ – Temperature of test mounting
- α_s – Thermal expansion of the standard gauge block
- δθ – Temperature difference of the gauge blocks

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Modeling Concept

Influence quantities as distributions

```

<influence id="tq" name="Average temperature deviation">
  <distribution>
    <gauss>
      <mu>0.1</mu>
      <sigma>0.2</sigma>
    </gauss>
  </distribution>
</influence>
            
```

$\theta = \theta_0 + \Delta$

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Modeling Concept

- Equation of the measurand

$$L = \frac{L_s [1 + \alpha_s (\theta - \delta\theta)] + d}{1 + (\alpha_s + \delta\alpha)\theta}$$
- Sub-influences

$$\theta = \theta_0 + \Delta$$

$$d = D + d_1 + d_2$$

Length L

- L_s – Calibration of the standard gauge block
- d – Measured difference of the gauge block
 - D – Repeated measurement
 - d_1 – Random comparator influences
 - d_2 – Systematic comparator influences
- $\delta\alpha$ – Difference of the thermal expansion coefficient of the gauge block
- θ – Temperature of test mounting
 - θ_0 – Mean Temperature of test mounting
 - Δ – Periodical variation of the room temperature
- α_s – Thermal expansion of the standard gauge block
- $\delta\theta$ – Temperature difference of the gauge blocks

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Modeling Concept

Modeling of complex influence quantities

```

<influence id="t" name="Deviation of temperature">
  <formula>tq + delta</formula>
  <influences>
    <influence id="tq" name="Average temperature deviation">
      <distribution>
        <gauss>
          <mu>0.1</mu>
          <sigma>0.2</sigma>
        </gauss>
      </distribution>
    </influence>
    <influence id="delta" name="Effect of cyclic temperature variation">
      <distribution>
        <arcsine>
          <lower>-0.5</lower>
          <upper>0.5</upper>
        </arcsine>
      </distribution>
    </influence>
  </influences>
</influence>
    
```

$$\theta = \theta_0 + \Delta$$

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Modeling Concept

- Equation of the measurand

$$L = \frac{L_s [1 + \alpha_s (\theta - \delta\theta)] + d}{1 + (\alpha_s + \delta\alpha) \theta}$$
- Sub-influences

$$\theta = \theta_0 + \Delta$$

$$d = D + d_1 + d_2$$

Length L

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Modeling Concept

Complete model of gauge block calibration

```

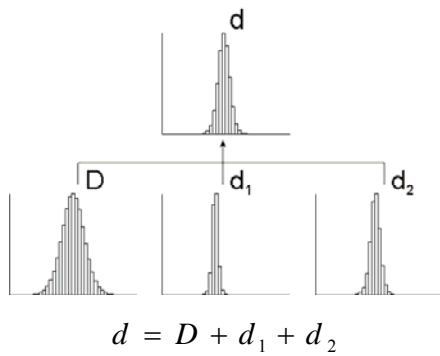
<model name="length" targetid="l">
  <influence id="l" name="Length">
    <formula>(ls * (1 + as * (t - dt)) + d) / (1 + t * (as + da))</formula>
  </influence>
  <influences>
    <influence id="ls" name="Calibration of reference standard">
    <influence id="d" name="Length of the reference standard">
    <influence id="as" name="Thermal expansion coefficient">
    <influence id="t" name="Deviation of temperature">
    <influence id="da" name="Difference in expansion coefficient">
    <influence id="dt" name="Difference in temperatures">
  </influences>
</model>

```

$$L = \frac{L_s [1 + \alpha_s (\theta - \delta\theta)] + d}{1 + (\alpha_s + \delta\alpha) \theta}$$

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Modeling Concept



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Modeling Concept

Operating System	Number of Evaluations
Windows Vista	10^6
	10^7
	10^8
Linux (openSUSE)	10^6
	10^7
	10^8

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Beyond GUM-SP1

Use of *sensitivity coefficients* for the calculation of the effect of an individual influence quantity on the overall measurement uncertainty

1. Usage of quadratic terms:

$$w_{quad}(x_i) = \frac{c_i^2 u^2(x_i)}{\sum_{j=1}^n c_j^2 u^2(x_j)} = \frac{c_i^2 u^2(x_i)}{u^2(y)}$$

2. Usage of absolute terms:

$$w_{abs}(x_i) = \frac{|c_i| u(x_i)}{\sqrt{\sum_{j=1}^n c_j^2 u^2(x_j)}} = \frac{|c_i| u(x_i)}{u(y)}$$

Beyond GUM-SP1

1) Simulate

- All influence quantities generate random numbers
- Calculate *mean* and *standard deviation* for each influence quantity during the simulation

2) Simulate

- A part of the influence quantities are “locked” to the previously calculated mean value (The effect of influence quantities are „*silenced*“)

Beyond GUM-SP1

Possible Scenarios:

- Turn **on** only the investigated influence quantity
 - Only the investigated influence quantity generates random numbers

```

<simulation>
  <init>
    <instance name="length" model="length"/>
  </init>
  <calculation mcsimulations="100">
    <fadeoutlist mode="all" type="oneon"/>
    <analyse mode="on" histbars="40" datafiles="delete"/>
    <uncertainty>length</uncertainty>
  </calculation>
</simulation>

```

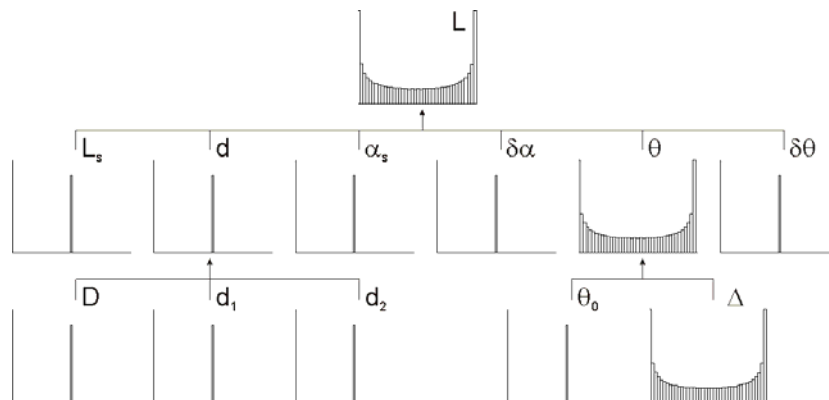
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Beyond GUM-SP1

1. Option: Turn on only the investigated influence



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Beyond GUM-SP1

Possible Scenarios:

- Turn only the investigated influence quantity **off**
 - All others generate random numbers as beforehand

```

<simulation>
  <init>
    <instance name="length" model="length"/>
  </init>
  <calculation mcsimulations="100">
    <fadeoutlist mode="all" type="oneoff"/>
    <analyse mode="on" histbars="40" datafiles="delete"/>
    <uncertainty>length</uncertainty>
  </calculation>
</simulation>

```

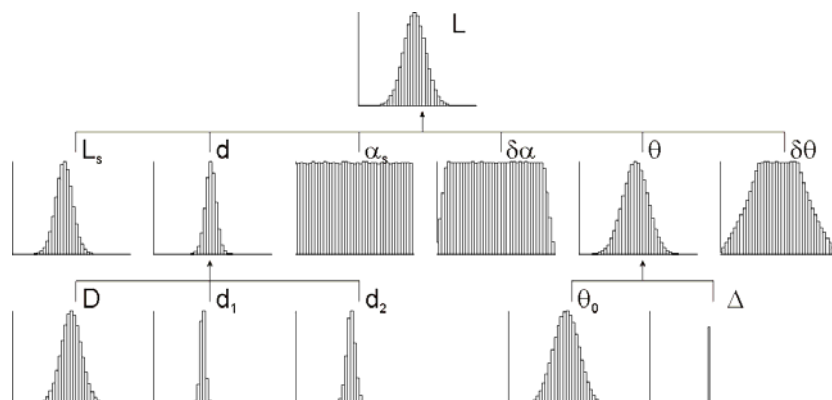
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Beyond GUM-SP1

2. Option: Turn only the investigated influence off



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Beyond GUM-SP1

Classical GUM

- Quadratic terms

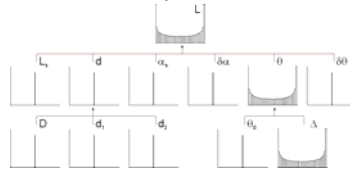
$$w_{quad}(x_i) = \frac{c_i^2 u^2(x_i)}{\sum_{j=1}^n c_j^2 u^2(x_j)} = \frac{c_i^2 u^2(x_i)}{u^2(y)}$$

- Absolute values

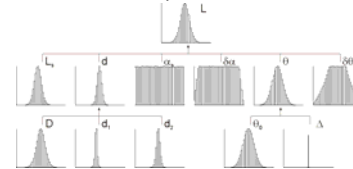
$$w_{abs}(x_i) = \frac{|c_i| u(x_i)}{\sqrt{\sum_{j=1}^n c_j^2 u^2(x_j)}} = \frac{|c_i| u(x_i)}{u(y)}$$

Monte Carlo Method

- Turn all off except one



- Turn all on except one

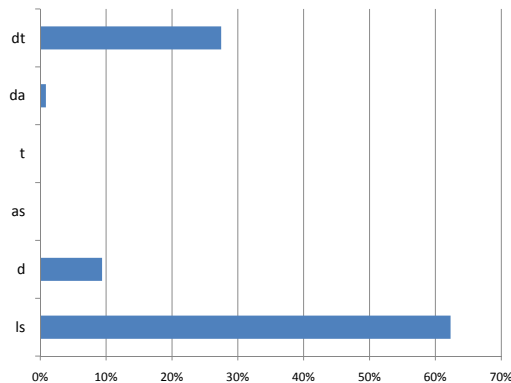


Beyond GUM-SP1

- GUF with quadratic terms: $w_{quad}(x_i) = \frac{c_i^2 u^2(x_i)}{\sum_{j=1}^n c_j^2 u^2(x_j)} = \frac{c_i^2 u^2(x_i)}{u^2(y)}$

Influence	GUF Quad	
	$c^2 u^2(x_i)$	Percent
I	1003	
ls	625	62.31%
d	94.09	9.38%
as	0	0.00%
t	0	0.00%
da	8.41	0.84%
dt	275.56	27.47%
Sum	1003.06	100.00%

GUF²

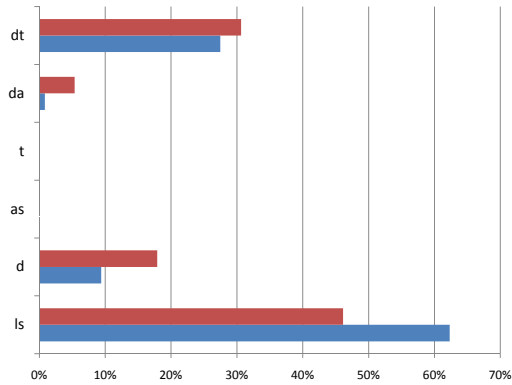


Beyond GUM-SP1

- GUF with absolute values: $w_{abs}(x_i) = \frac{|c_i|u(x_i)}{\sqrt{\sum_{j=1}^n c_j^2 u^2(x_j)}} = \frac{|c_i|u(x_i)}{u(y)}$

Influence	GUF abs	
	c _i u(x _i)	Percent
l	32	
ls	25	46.13%
d	9.7	17.90%
as	0	0.00%
t	0	0.00%
da	2.9	5.35%
dt	16.6	30.63%
Sum	54.2	100.00%

■ |GUF|
■ GUF²



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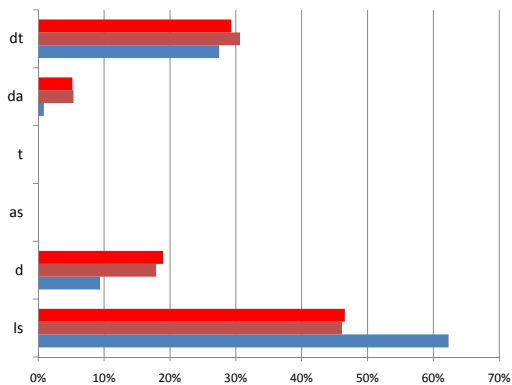
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Beyond GUM-SP1

- Monte Carlo method
 - Turn all off except one influence

Influence	MCM – One on	
	Std	Percent
l	36	
ls	27	46.55%
d	11	18.97%
as	0	0.00%
t	0	0.00%
da	3	5.17%
dt	17	29.31%
Sum	58	100.00%

■ MCM – One on
■ |GUF|
■ GUF²



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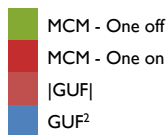
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Beyond GUM-SP1

- Monte Carlo method
 - Turn one influence quantity off

Influence	MCM - One off		
	Std	Difference	Percent
l	36		
ls	24	12	33.33%
d	34	2	5.56%
as	36	0	0.00%
t	34	2	5.56%
da	34	2	5.56%
dt	31	5	13.89%



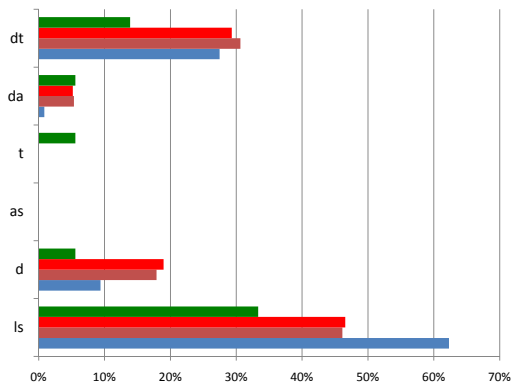
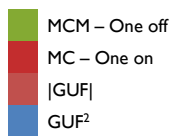
Important:

- Sum of the der percentage contributions is *not* 100%
- Direct comparison with the other methods only possible to a limited extent
- Percentage illustrates the *maximal reduction* of the measurement uncertainty through optimizing this influence

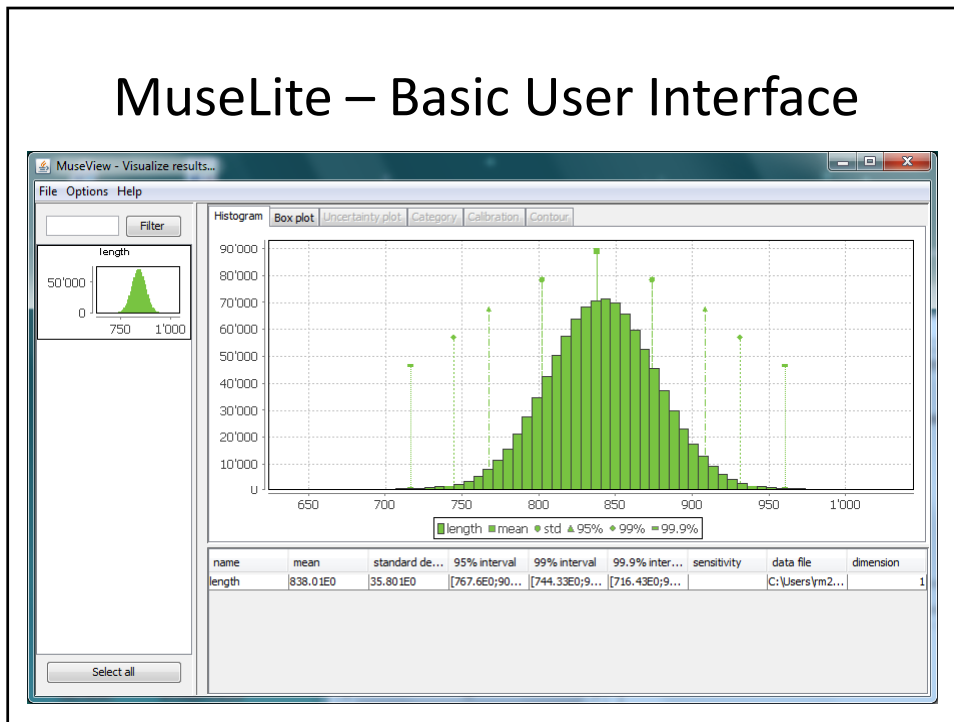
Beyond GUM-SP1

- Monte Carlo method
 - Turn one influence quantity off

Influence	MCM - One off		
	Std	Difference	Percent
l	36		
ls	24	12	33.33%
d	34	2	5.56%
as	36	0	0.00%
t	34	2	5.56%
da	34	2	5.56%
dt	31	5	13.89%



MuseLite – Basic User Interface



Thank You Very Much

- Simulation framework MUSE
 - Concepts of GS1 and additional new approaches realized in one framework
 - Entire implementation in C/C++
 - Robust long-run behavior (memory usage & computational time)
(MUSE: Computational aspects of a GUM-supplement 1 implementation, Metrologia, 45, p586-593, 2008)
- Structured Modeling in XML
 - Stored in a pure text file
 - Open and easy complementary format
 - Strict language definition in XML
- Beta version available on:
<http://sourceforge.net/projects/freemuse/files/>